int motor = 3;

int LEDg = 4;

int LEDy = 5;

int LEDr = 7;

void setup() {

// put your setup code here, to run once:

// tohle je first pokus motorem

pinMode (3,OUTPUT);

pinMode (4,OUTPUT);

pinMode (5,OUTPUT);

}

void loop() {

// put your main code here, to run repeatedly:

analogWrite (motor,0);

digitalWrite (LEDr,HIGH);

delay (3000);

digitalWrite (LEDr,LOW);

analogWrite (motor,150);

digitalWrite (LEDy,HIGH);

delay (2000);

digitalWrite (LEDy,LOW);

analogWrite (motor,250);

digitalWrite (LEDg,HIGH);

delay (4000);

digitalWrite (LEDg,LOW);

}